On the Complexity of Partial Order Trace Model Checking

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1 Introduction

The design of a distributed system is known to be a difficult task which can be eased by various techniques including validation and debugging. The model-based design abstracts the actions the system can do into events which change its global state. Depending on the various assumptions the designer can make, the model can be either centralized, providing a global observation and control on the entire system or distributed where each event is local to some process and asynchronous communications allow the concurrent processes to communicate. The model validation checks that it has the required properties, usually expressed by temporal logic formulae, e.g. in CTL*, Ctl or Ltl [2].

In practice, this abstraction is generally not sufficient to avoid the state-explosion problem which prevents the designer from exhaustively verifying the whole system, even with efficient exploration techniques such as partial order reduction or symbolic model checking [2]. The designer may therefore want to analyse or validate simpler models which describe only some facets of the system. As such, it may be important, during the early design phases, to check scenarios expressed for instance by Message Sequence Charts [5]. During the testing and deployment phases, executions must be validated; runtime verification techniques [4] are typically designed for that purpose. The practical validity of these methods depend on the number of test-cases, to give a reasonable confidence that the system is correct. Therefore, theoretical and practical efficiency...
of the algorithms able to solve the problem are crucial. In the centralized case, an execution of the system is a sequence of events. The complexity of determining if such an execution satisfies a property has been studied in [7] where it is shown that the problem can be solved efficiently. In the distributed case, the exact order in which two concurrent events occur in the execution is, in general, not always known or guaranteed. By taking into account the communications between processes, however, a partial order on the events of the execution can still be obtained. Hence in this case, an execution can be viewed as a partially ordered set of events called partial order trace. The global properties satisfaction on these partial order traces has been widely studied since the 90’s. Chase and Garg have shown in [1], that the global predicate detection problem, i.e. the reachability of a system’s state which satisfies some global predicate, is NP-complete for an arbitrary predicate, even when there is no inter-process communication. However, various classes of properties can be checked efficiently in polynomial time (see e.g. [3, 6] which relates these methods). Sen and Garg extended the study to temporal operators and defined the RCTL logic [9], a restricted form of CTL whose model checking is polynomial on partial order traces. In previous works, we developed symbolic LTL [3] and CTL [6] model checking of partial order traces and showed their efficiency in practice.

We study here the theoretical complexity of CTL*, CTL and LTL model checking over finite partial order traces. We show that over such partial order traces, CTL* and CTL model checking are PSPACE-complete and that the LTL model checking is coNP-complete.

2 Basic definitions

In this section, we recall the satisfiability problems for propositional and quantified propositional formulae. In the rest of the paper, we assume an infinite and countable set \( P \) of propositions and \( \mathbb{B} \) denotes the set of Boolean values, i.e. \( \mathbb{B} = \{ \text{tt}, \text{ff} \} \) where \( \text{tt} \) stands for true and \( \text{ff} \) for false.

Propositional Boolean Formulae A Propositional Boolean Formula (PBF) \( \phi \) is defined using the following grammar: \( \phi ::=} \top | p | \neg \phi | \phi \lor \phi \), where \( \top \) denotes the true formula, and \( p \in P \).

Moreover, let \( \bot \) denotes the formula \( \neg \top \) (the false formula). Other standard Boolean operators \( \land, \Rightarrow, \iff \) are derived as usual. The (finite) set of propositions appearing in a PBF formula \( \phi \) is denoted by \( P(\phi) \). A PBF \( \phi \) is interpreted using a valuation of \( P(\phi) \), i.e. a function \( v : P(\phi) \mapsto \mathbb{B} \).

The satisfaction of a PBF \( \phi \) by a valuation \( v \), noted \( v \models \phi \), is defined as usual. The PBF \( \phi \) is satisfiable if there exists a valuation \( v \) such that \( v \models \phi \). The size of the PBF \( \phi \), noted \(|\phi|\), is defined inductively as follows: (i) if \( \phi = \top \) or \( \phi = p \) then \(|\phi| = 1 \), (ii) if \( \phi = \neg \phi_1 \) then \(|\phi| = |\phi_1| + 1 \) and (iii) if \( \phi = \phi_1 \lor \phi_2 \) then \(|\phi| = |\phi_1| + |\phi_2| + 1 \). Finally, given a PBF \( \phi \), the PBF-SAT problem consists in determining if \( \phi \) is satisfiable. This problem is known to be NP-complete [8].
Quantified Boolean Formulae A Quantified Boolean Formula (QBF) $\psi$ is a formula of the form $Q_1p_1 \cdot Q_2p_2 \cdot \ldots \cdot Q_np_n \cdot \phi$ where (i) $\phi$ is a PBF over $\mathbb{P}$ and (ii) $Q_i \in \{\exists, \forall\}$ and $p_i \in P(\phi)$ for $i \in [1, r)$. Note that a PBF is a QBF without quantifiers ($r = 0$). In the following, we assume that each proposition is quantified at most once. A fully QBF is a QBF where all propositions are quantified. QBF are also interpreted over valuations. As in the PBF case, $P(\psi)$ denotes the set of propositions appearing in the QBF $\psi$. A valuation $v : P(\psi) \mapsto \mathbb{B}$ satisfies a QBF $\psi$ is noted $v \models \psi$. The satisfaction is derived from the propositional case as follows. If $\psi = \forall p \cdot \psi'$, then $v \models \psi$ iff $v[p \mapsto \text{tt}] \models \psi'$ and $v[p \mapsto \text{ff}] \models \psi'$ and, if $\psi = \exists p \cdot \psi'$, then $v \models \psi$ iff $v[p \mapsto \text{tt}] \models \psi'$ or $v[p \mapsto \text{ff}] \models \psi'$. Note that the truth value of a QBF formula $\psi$ depends only on the valuation of its free propositions, i.e. those used in $\psi$ and not linked by a quantifier. In particular, if $\psi$ is a fully QBF, its truth value does not depend on $v$. Similarly to PBF, a QBF $\psi$ is satisfiable if there exists a valuation $v$ such that $v \models \psi$. The size of a QBF $\psi = Q_1p_1 \cdot Q_2p_2 \cdot \ldots \cdot Q_np_n \cdot \phi$ where $\phi$ is a PBF, noted $|\psi|$, is equal to $|\phi|$. Note that the number of quantifiers in $\psi$ is bounded by $|\phi|$. Given a (fully) QBF $\psi$, the QBF-SAT problem consists in deciding if $\psi$ is satisfiable. This problem is known to be $PSPACE$-complete, even for fully QBF [8].

3 CTL*, CTL and LTL over partial order traces

Partial Order Traces A partial order trace (po-trace) is a tuple $T = (E, P_0, \alpha, \beta, \preceq)$ where (i) $E$ is a finite set of events; (ii) $P_0 \subseteq P$ is the finite set of propositions initially true; (iii) $\alpha : E \mapsto 2^P$ (resp. $\beta : E \mapsto 2^P$) is a function giving for each event $e$ the finite set of propositions set to $\text{tt}$ (resp. $\text{ff}$) such that $\forall e \in E : \alpha(e) \cap \beta(e) = \emptyset$; and (iii) $\preceq \subseteq E \times E$ is a partial order relation on $E$ such that $\forall e, e' \in E : ((\alpha(e) \cup \beta(e)) \cap (\alpha(e') \cup \beta(e'))) \neq \emptyset \Rightarrow (e \preceq e') \lor (e' \preceq e)$, i.e. if the truth value of at least one proposition is modified by two events, then those events must be ordered. Given an event $e \in E$, we define $|e| = \{e' \in E \mid e' \preceq e\}$, the past of $e$ (including $e$ itself). The finite set of propositions used by $T$ is denoted by $P(T)$, i.e $P(T) = P_0 \cup \bigcup_{e \in E} \left(\alpha(e) \cup \beta(e)\right)$. A cut is a subset $C \subseteq E$ such that $\forall e \in C : \not\exists e' \sqsubseteq C$. The set of cuts is denoted by $\text{cuts}(T)$. Given a cut $C \in \text{cuts}(T)$, we define enabled($C$) = $\{e \in E \setminus C \mid (\alpha(e) \setminus \{e\}) \subseteq C\}$ the set of events enabled in $C$, and $C/p = \{e \in C \mid p \in \alpha(e) \cup \beta(e)\}$ the set of events of $C$ that modifies the truth value of $p$. Note that for every proposition $p$, the set $C/p$ is totally ordered. The set of propositions true in a cut $C$, noted $P_C$ is then defined as $\{p \in P(T) \mid (C/p = \emptyset \land p \in P_0) \lor (C/p \neq \emptyset \land p \in \alpha(\max(C/p)))\}$. If an event $e$ is enabled in the cut $C$, then it can be fired from $C$ leading to $C' = C \cup \{e\}$, noted $C \rightarrow C'$. A path $\sigma$ is a sequence $\sigma = C_0\ldots C_k \in \text{cuts}(T)^*$ such that $k \geq 0$ and $\forall i \in [0,k) : C_i \triangleright C_{i+1}$. The size $|\sigma|$ of the sequence $\sigma$ is the number of firings from $C_0$ in $\sigma$ (i.e. $k$ here)\footnote{Note that $|\sigma|$ could also have been defined as its number of states (i.e. $k + 1$ here)}; and we note $\sigma^i$ the suffix $C_i, C_{i+1}, \ldots, C_k$. $\sigma^i$ is left undefined if $i > |\sigma|$. A run from a cut $C$ is a path $\sigma = C_0 \ldots C_k$
with (i) $C_0 = C$ and (ii) $C_k = E$. The set of runs starting in a cut $C \in \text{cuts}(T)$ is denoted by $\text{runs}(C)$. The size of the po-trace $T = \langle E, P_0, \alpha, \beta, \preceq \rangle$, noted $|T|$, is equal to $|E| + |\beta| + |P(T)|$.

$\text{CTL}^*$ Formulæ in the temporal logic $\text{CTL}^*$ are defined using the following grammar:

$$\begin{align*}
\Psi &::= \top \mid p \mid \neg \Psi \mid \Psi \lor \Psi \mid \exists \phi \mid \forall \phi \\
\Phi &::= \Psi \mid \neg \Psi \mid \phi \lor \Psi \mid \phi \lor \Psi \lor \phi \lor \phi \lor \Phi \lor \Phi
\end{align*}$$

where $\Psi$ is a state formula, $\Phi$ is a path formula, $p \in P$, $\mathcal{U}$ is the until operator and $\mathcal{O}$ is the next operator. Other Boolean constructs ($\perp, \land, \Rightarrow, \Leftrightarrow$) are defined as in the PBF case. In our case, $\text{CTL}^*$ state (resp. path) formulæ are interpreted over cuts $C$ (paths $\sigma$) of a po-trace $T$. The satisfaction relation, noted $\models_C$ (resp. $\models_\sigma$) for state (resp. path) formulæ, is the smallest relation that satisfies the following:

$$\begin{align*}
\langle T, C \rangle &\models_C \top \\
\langle T, C \rangle &\models_C p \quad \forall \; p \in P_C \\
\langle T, C \rangle &\models_C \neg \Psi \quad \text{iff} \quad \langle T, C \rangle \not\models_C \Psi \\
\langle T, C \rangle &\models_C \Psi_1 \lor \Psi_2 \quad \text{iff} \quad \langle T, C \rangle \models_C \Psi_1 \lor \langle T, C \rangle \models_C \Psi_2 \\
\langle T, C \rangle &\models_C \exists \phi \quad \text{iff} \quad \exists \sigma \in \text{runs}(C) : \langle T, \sigma \rangle \models_\sigma \phi \\
\langle T, C \rangle &\models_C \forall \phi \quad \text{iff} \quad \forall \sigma \in \text{runs}(C) : \langle T, \sigma \rangle \models_\sigma \phi \\
\langle T, \sigma \rangle &\models_\sigma \Psi \quad \text{iff} \quad \langle T, C_0 \rangle \models_C \Psi \\
\langle T, \sigma \rangle &\models_\sigma \neg \phi \quad \text{iff} \quad \langle T, \sigma \rangle \not\models_\sigma \phi \\
\langle T, \sigma \rangle &\models_\sigma \phi_1 \lor \phi_2 \quad \text{iff} \quad \langle T, \sigma \rangle \models_\sigma \phi_1 \lor \langle T, \sigma \rangle \models_\sigma \phi_2 \\
\langle T, \sigma \rangle &\models_\sigma \mathcal{O} \phi \quad \text{iff} \quad |\sigma| > 0 \land \langle T, \sigma^i \rangle \models_\sigma \phi \\
\langle T, \sigma \rangle &\models_\sigma \phi_1 \mathcal{U} \phi_2 \quad \text{iff} \quad \exists i \in [0, |\sigma|] : ((\langle T, \sigma^i \rangle \models_\sigma \phi_2) \land (\forall j \in [0, i) : \langle T, \sigma^j \rangle \models_\sigma \phi_1))
\end{align*}$$

where $\sigma = C_0 \ldots C_k$, $\Phi, \Phi_1, \Phi_2$ are path formulæ and $\Psi, \Psi_1, \Psi_2$ are state formulæ.

A po-trace $T$ satisfies a $\text{CTL}^*$ state formula $\Psi$, noted $T \models \Psi$, if $\langle T, \emptyset \rangle \models_C \Psi$. The size of a $\text{CTL}^*$ formula $\Psi$, noted $|\Psi|$, is defined inductively as follows: (i) if $\Psi = \top$ or $\Psi = p$ then $|\Psi| = 1$; (ii) if $\Psi = \neg \Psi_1$, $\Psi = \mathcal{O} \Psi_1$, $\Psi = \exists \Psi_1$ or $\Psi = \forall \Psi_1$ then $|\Psi| = |\Psi_1| + 1$; if $\Psi = \Psi_1 \lor \Psi_2$ or $\Psi = \Psi_1 \mathcal{U} \Psi_2$ then $|\Psi| = |\Psi_1| + |\Psi_2| + 1$. $\text{CTL}^*$ has in particular two useful fragments:

**Computation Tree Logic (CTL)** is a fragment of $\text{CTL}^*$ in which each $\mathcal{O}$ and $\mathcal{U}$ operators must be immediately preceded by a path quantifier. Formally, a CTL formula $\Psi$ is defined using the grammar:

$$\begin{align*}
\Psi &::= \top \mid p \mid \neg \Psi \mid \Psi \lor \Psi \mid \exists \phi \mid \forall \phi \\
\Phi &::= \Psi \mid \neg \Psi \mid \phi \lor \Psi \mid \phi \lor \Psi \lor \phi \lor \phi \lor \Phi \lor \Phi
\end{align*}$$

**Linear Time Logic (LTL)** is another fragment of $\text{CTL}^*$ in which each formula has the form $\forall \Phi$ and the only state sub-formulæ permitted are $\top$ and atomic propositions $p \in P$. Formally, an LTL formula $\Psi$ is defined using the grammar:

$$\begin{align*}
\Psi &::= \forall \Phi \\
\Phi &::= \top \mid p \mid \neg \Phi \mid \Phi \lor \Phi \mid \mathcal{O} \Phi \mid \mathcal{U} \Phi
\end{align*}$$

Given a po-trace $T$ and a formula $\Psi$, the model checking problem consists in determining if $T \models \Psi$. In the remainder of the paper, we investigate the complexity of the model checking problem for $\text{CTL}^*$, CTL and LTL formulæ.
4 CTL* and CTL Model Checking

We start with the model checking problem for CTL* and CTL. First, we will show that for CTL, the problem is PSPACE-hard. Since CTL is a fragment of CTL*, it implies that the problem for CTL* is also PSPACE-hard. Then, we show that, for CTL*, the problem is PSPACE-easy. Again, since CTL is a fragment CTL*, it follows that the problem for CTL is also PSPACE-easy. Those results allow us to conclude that for CTL* and CTL, the model checking problem is PSPACE-complete.

In order to prove that for CTL, the model checking problem is PSPACE-hard, we exhibit a polynomial reduction of (fully) QBF-SAT. that works as follows. Let \( \psi \) be a fully QBF with \( P(\psi) = \{p_1, \ldots, p_r\} \). We build a po-trace \( T_{P(\psi)} \) and a CTL formula \( \Psi_\psi \) and prove that \( \psi \) is satisfiable if \( T_{P(\psi)} \models \Psi_\psi \).

The po-trace \( T_{P(\psi)} = (E, P_0, \alpha, \beta, \leq) \) is built over set of propositions \( \bigcup_{i \in [1,r]} \{q_i, q'_i\} \) as follows:

(i) \( E = \bigcup_{i \in [1,r]} \{e_i, e'_i\} \);
(ii) \( P_0 = \emptyset \);
(iii) \( \forall i \in [1,r] : \alpha(e_i) = \{q_i\} \land \beta(e_i) = \emptyset \land \alpha(e'_i) = \{q'_i\} \land \beta(e'_i) = \emptyset \).

The CTL formula \( \Psi_\psi \) is defined inductively as follows:

\[
\Psi_\psi = \begin{cases} 
\psi[p_1 \leftarrow \text{eval}_{p_1}^{\Phi_\psi}, \ldots, p_r \leftarrow \text{eval}_{p_r}^{\Phi_\psi}] & \text{if } \psi \text{ is a PBFF} \\
\exists \bigcirc ((\text{eval}_{p_1}^{\Phi} \lor \text{eval}_{p_1}^{\Phi_\psi}) \land \Psi_\psi) & \text{if } \psi = \exists p_i \cdot \psi_1 \\
\forall \bigcirc ((\text{eval}_{p_1}^{\Phi} \lor \text{eval}_{p_1}^{\Phi_\psi}) \Rightarrow \Psi_\psi) & \text{if } \psi = \forall p_i \cdot \psi_1 
\end{cases}
\]

where \( \text{eval}_{p_i}^{\Phi} = \{q_i \land \neg q'_i\}, \text{eval}_{p_i}^{\Phi_\psi} = \{\neg q_i \land q'_i\} \), and where \( \psi[p_1 \leftarrow \phi_1, \ldots, p_r \leftarrow \phi_r] \) denotes the formula \( \psi \) where every occurrence of proposition \( p_i \) is replaced by the formula \( \phi_i \) for \( i \in [1,r] \). As a first remark, it is clear that the sizes of \( \Psi_\psi \) and \( T_{P(\psi)} \) are polynomial in the size of \( \psi \). Indeed, each proposition in \( \psi \) is replaced by a sub-formula of (constant) size 4 and each quantification is replaced by a construct of (constant) size 12. In the following, for any \( i \in [1,r] \), we note \( C_{p_i}^\Phi = \{e_i\}, \) resp. \( C_{p_i}^\Phi = \{e'_i\} \), the minimal cut satisfying \( \text{eval}_{p_i}^{\Phi} \), resp. \( \text{eval}_{p_i}^{\Phi_\psi} \). Formally, \( \langle T_{P(\psi)}, C_i^\Phi \rangle \models_C \text{eval}_{p_i}^{\Phi} \) and \( \langle T_{P(\psi)}, C_i^\Phi \rangle \models_C \text{eval}_{p_i}^{\Phi_\psi} \) since \( P_{C_{p_i}} = \{q_i\} \) and \( P_{C_{p_i}} = \{q'_i\} \).

**Lemma 1** Given a fully QBF \( \psi \), \( T_{P(\psi)} \models \Psi_\psi \) iff \( \psi \) is satisfiable.

**Proof.** We prove by induction on \( |P(\psi)| \) that \( \psi \) is satisfiable iff \( \langle T_{P(\psi)}, \emptyset \rangle \models_C \Psi_\psi \).

**Base cases.** If \( |P(\psi)| = 0 \), then \( P(\psi) = \emptyset \) and \( \psi \) is a Boolean combination of \( T \). If \( \psi \Leftrightarrow \top \), by definition of \( \Psi_\psi \), we have \( \Psi_\psi = \psi[p_1 \leftarrow \text{eval}_{p_1}^{\Phi_\psi}, \ldots, p_r \leftarrow \text{eval}_{p_r}^{\Phi_\psi}] = \psi \Leftrightarrow \top \). In this case, we have that \( \langle T_{P(\psi)}, \emptyset \rangle \models_C \Psi_\psi \). If \( \psi \Leftrightarrow \bot \), \( \Psi_\psi \Leftrightarrow \bot \), hence \( \langle T_{P(\psi)}, \emptyset \rangle \not\models_C \Psi_\psi \). We conclude that \( \langle T_{P(\psi)}, \emptyset \rangle \models_C \Psi_\psi \) iff \( \psi \) is satisfiable.

**Induction cases.** We have to consider two cases: • The first case is when \( \psi = \exists p_i \cdot \psi_1 \). In this case, \( \psi \) is satisfiable iff \( \psi_1[p_i \leftarrow \top] \) or \( \psi_1[p_i \leftarrow \bot] \) is satisfiable. By induction, this is
equivalent to \( \langle T_{P(\psi)\setminus \{p_i\}}, \emptyset \rangle \models_C \Psi_{\psi_1[p_i \leftarrow \top]} \) or \( \langle T_{P(\psi)\setminus \{p_i\}}, \emptyset \rangle \models_C \Psi_{\psi_1[p_i \leftarrow \bot]} \). By definition of \( \Psi_{\psi_1} \), this holds if \( \langle T_{P(\psi)\setminus \{p_i\}}, \emptyset \rangle \models_C \Psi_{\psi_1[q_i \leftarrow \top, q_i' \leftarrow \bot]} \) or \( \langle T_{P(\psi)\setminus \{p_i\}}, \emptyset \rangle \models_C \Psi_{\psi_1[q_i \leftarrow \bot, q_i' \leftarrow \top]} \), and by definition of \( C_1^{tt} \) and \( C_1^{ff} \), if \( \langle T_{P(\psi)}, C_1^{tt} \rangle \models_C \Psi_{\psi_1} \) or \( \langle T_{P(\psi)}, C_1^{ff} \rangle \models_C \Psi_{\psi_1} \). Now since \( C_1^{tt} \) (resp. \( C_1^{ff} \)) contains the only event that can satisfy \( \text{eval}^{tt} \) (resp. \( \text{eval}^{ff} \)), we deduce that \( \langle T_{P(\psi)}, C_1^{tt} \rangle \models_C \Psi_{\psi_1} \) iff \( \langle T_{P(\psi)}, \emptyset \rangle \models_C \exists \psi (\text{eval}^{tt} \land \Psi_{\psi_1}) \) for any \( b \in B \). We can therefore conclude that \( \psi \) is satisfiable if \( \langle T_{P(\psi)}, \emptyset \rangle \models_C \exists \psi (\text{eval}^{tt} \land \Psi_{\psi_1}) \) or \( \langle T_{P(\psi)}, \emptyset \rangle \models_C \exists \psi (\text{eval}^{ff} \land \Psi_{\psi_1}) \), or equivalently if \( \langle T_{P(\psi)}, \emptyset \rangle \models_C (\exists \psi \text{eval}^{tt} \land \Psi_{\psi_1}) \lor (\exists \psi \text{eval}^{ff} \land \Psi_{\psi_1}) \). Finally, the last formula is equivalent to \( \exists \psi ((\text{eval}^{tt} \lor \text{eval}^{ff}) \land \Psi_{\psi_1}) = \Psi_\psi \).

- The second case is when \( \psi = \forall p_i \psi_1 \). In this case, \( \psi \) is satisfiable iff \( \psi_1[p_i \leftarrow \top] \) and \( \psi_1[p_i \leftarrow \bot] \) are satisfiable. Similarly to the first case, by induction, definition of \( \Psi_{\psi_1} \), \( C_1^{tt} \) and \( C_1^{ff} \), this holds if \( \langle T_{P(\psi)}, C_1^{tt} \rangle \models_C \Psi_{\psi_1} \) and \( \langle T_{P(\psi)}, C_1^{ff} \rangle \models_C \Psi_{\psi_1} \). Note that for any cuts \( C \) such that \( 0 \prec C \) either \( C = C_b^0 \) with \( b \in B \) and \( C \models \text{eval}^{tt} \), or \( C \not\models \text{eval}^{tt} \lor \text{eval}^{ff} \). We deduce that \( \langle T_{P(\psi)}, C_0^b \rangle \models_C \Psi_{\psi_1} \) iff \( \langle T_{P(\psi)}, \emptyset \rangle \models_C \forall \psi \text{eval}^{tt} \Rightarrow \Psi_{\psi_1} \) for any \( b \in B \). We can therefore conclude that \( \psi \) is satisfiable iff \( \langle T_{P(\psi)}, \emptyset \rangle \models_C \forall \psi \text{eval}^{tt} \Rightarrow \Psi_{\psi_1} \) and \( \langle T_{P(\psi)}, \emptyset \rangle \models_C \forall \psi \text{eval}^{ff} \Rightarrow \Psi_{\psi_1} \), or equivalently if \( \langle T_{P(\psi)}, \emptyset \rangle \models_C (\forall \psi \text{eval}^{tt} \Rightarrow \Psi_{\psi_1}) \lor (\forall \psi \text{eval}^{ff} \Rightarrow \Psi_{\psi_1}) \). Finally, the last formula is equivalent to \( \forall \psi ((\text{eval}^{tt} \lor \text{eval}^{ff}) \Rightarrow \Psi_{\psi_1}) = \Psi_\psi \).

From Lem. 1, we get the PSPACE-hardness for \( \text{Ctl} \).

**Proposition 1** The model checking problem over po-traces is PSPACE-hard for \( \text{Ctl} \).

**Proof.** Since QBF-SAT is PSPACE-complete, \( \Psi_\psi \) and \( T_{P(\psi)} \) have size polynomial w.r.t. the size of a fully QBF \( \psi \), we conclude by Lem. 1 that the proposition holds.

Now, we show PSPACE-easiness of the model checking problem for \( \text{Ctl}^* \) by exhibiting a polynomial space algorithm that solves the problem.

**Proposition 2** The model checking problem over po-traces is PSPACE-easy for \( \text{Ctl}^* \).

**Proof.** First, we exhibit a recursive algorithm that takes a partial ordered trace \( T = (E, P_0, \alpha, \beta, \preceq) \), a \( \text{Ctl}^* \) state formula \( \Psi \) with a cut \( C \) (resp. a \( \text{Ctl}^* \) trace formula \( \Psi \) with a run \( \sigma = C_0 C_1 \ldots C_k \) with \( C = C_0 \)), and returns \text{true} \ if and only if \( \langle T, C \rangle \models_C \Psi \) (resp. \( \langle T, \sigma \rangle \models_\sigma \Psi \)). The recursion follows the structure of the inference which shows \( \langle T, C \rangle \models_C \Psi \) or \( \langle T, \sigma \rangle \models_\sigma \Psi \). Then, we show inductively on the depth of the recursion, that this algorithm is polynomial space w.r.t. the size of the formula \( \Psi \) and the size of the po-trace \( T \).

**Base cases.** • When \( \Psi = \top \) or \( \Psi = p \). In the first case, the algorithm always returns \text{true}. In the second case, if \( \Psi \) is a state formula then it builds \( P_C \) and returns \text{true} \ if \( p \in P_C \).

**Induction cases** If \( \sigma \) contains sub-formulae, then the algorithm works as follows:

- First, if \( \Psi \) is evaluated on a trace \( C = C_0 \ldots C_k \) but it is not of the form \( \Psi_1 \lor \Psi_2 \) or \( \neg \Psi_1 \lor \Psi_2 \), then \( \Psi \) is also a state formula and the algorithm returns \text{true} \ if \( \langle T, C_0 \rangle \models_C \Psi \).
• If \( \Psi = \neg \Psi_1, \Psi = \Psi_1 \lor \Psi_2 \), then \( \Psi_1 \) and \( \Psi_2 \) are first evaluated and then the algorithm evaluates \( \Psi \) according to the usual semantics of boolean connectors.

• If \( \Psi = Q \Psi_1 \) with \( Q \in \{\exists, \forall\} \), then \( \Psi \) is a state formula. In this case, the algorithm enumerates all the runs \( \sigma \in \text{runs}(C) \) and then checks if \( (T, \sigma) \models \Psi \) holds. In the case where \( Q = \exists \) (resp. \( Q = \forall \)), the algorithm returns \( \text{true} \) iff at least one run \( \sigma \in \text{runs}(C) \) (resp. all the runs \( \sigma \in \text{runs}(C) \)), is such that \( (T, \sigma) \models \Psi \).

• if \( \Psi = \bigcirc \Psi_1 \) then the algorithm returns \( \text{true} \) iff \( (T, C_1 \ldots C_k) \models \Psi \) holds.

• if \( \Psi = \Psi_1 \cup \Psi_2 \), then \( \Psi \) is a path formula. For each \( 0 \leq i \leq k \), the algorithm first considers the sub-formula \( \Psi_2 \) and checks if \( (T, C_i \ldots C_k) \models \Psi \) holds. If it is the case, the algorithm considers \( \Psi_1 \) and checks if \( (T, C_j \ldots C_k) \models \Psi \) holds for all \( 0 \leq j < i \). In the case of a positive answer for all \( 0 \leq j < i \), the algorithm returns \( \text{true} \). Finally, if the algorithm does not conclude for any \( 0 \leq i \leq k \) then it returns \( \text{false} \).

Let us now show that the algorithm uses only a polynomial space w.r.t. the size of the formula \( \Psi \) and the size of the partial order trace \( T \). To simplify the presentation, we do not care about the memory used to store one cut, \( P_C, \ldots \). However, it is immediate that the memory used can be bounded by a polynomial in the size of \( T \) by using, for instance, bit vectors to represent sets. More precisely, we show that the number of cuts that are computed and stored at the same time into memory by the algorithm is bounded by \(|T| \cdot |\Psi|\). The proof is by induction on the depth of the recursion of the algorithm used.

**Base cases** • If \( \Psi = T \), then the algorithm returns \( \text{true} \) in constant time without building cuts, hence the result.

• If \( \Psi = p \) then \( \Psi \) is evaluated on the cut \( C \) and the algorithm builds \( P_C \). This can be achieved in polynomial time without building new cuts by first computing for each \( p \in P(T) \) the set \( C/\cdot_p \).

This can be done by enumerating the events \( e \in C \) and checks if \( p \in \alpha(e) \cup \beta(e) \) (this can also be done by enumerating \( \alpha \) and \( \beta \)). If \( C/\cdot_p \) is empty then \( p \in P_C \) iff \( p \in P_0 \) (this can be checked by enumerating the elements of \( P_0 \)). Otherwise, we find the maximal element \( e_{\max} \) w.r.t. \( \preceq \) in \( C/\cdot_p \) by enumerating the elements in \( C/\cdot_p \) and \( \preceq \). Finally, \( p \) is in \( P_C \) iff \( p \in \alpha(e_{\max}) \).

Since \( 0 \leq |T| \cdot |\Psi| \), we conclude.

**Induction cases** • If \( \Psi = \neg \Psi_1 \) or \( \Psi = \Psi_1 \lor \Psi_2 \) then by induction hypothesis we know that the algorithm evaluates \( \Psi_1 \) and \( \Psi_2 \) (on runs or cuts) storing at most \(|T| \cdot (|\Psi| - 1)\) cuts (since \(|\Psi_i| < |\Psi|\) for \( i \in \{1, 2\} \)), hence it evaluates \( \Psi \) by storing at most \(|T| \cdot (|\Psi| - 1) \leq |T| \cdot |\Psi| \) cuts.

• If \( \Psi = Q \Psi_1 \) with \( Q \in \{\exists, \forall\} \), then the algorithm enumerates all the runs \( \sigma \in \text{runs}(C) \). This can be done as follows: From \( C' \) initially equal to \( C \), we enumerate the events \( e \in E \) and then test if \( e \in \text{enabled}(C') \) and if there is no \((e', e) \in \preceq \) such that \( e' \notin C' \) by enumerating the elements of \( \preceq \) and \( C' \). If it is the case, we iterate from the cut \( C' \cup \{e\} \) until we build \( E \). At each step, the algorithm only keeps in memory the cuts of the current investigated run. Since the size of
the runs are bounded by $|E|$, hence bounded by $|\mathcal{T}|$, the number of cuts stored in memory when enumerating all the runs $\sigma \in \text{runs}(C)$ is bounded by $|\mathcal{T}|$. Then, by induction hypothesis, the algorithm uses memory bounded by $|\mathcal{T}| \cdot |\Psi_1|$ to check if $\langle \mathcal{T}, \sigma \rangle \models_{\sigma} \Psi_1$ holds. Since $|\Psi_1| + 1 = |\Psi|$, we conclude that the algorithm maintains at most $|\mathcal{T}| \cdot |\Psi|$ cuts in memory when evaluating $\Psi$.

- If $\Psi = \bigcirc \Psi_1$, the algorithm evaluates $\Psi_1$ on a trace. By induction hypothesis, this is achieved by storing at most $|\Psi_1| \cdot |\mathcal{T}|$ cuts. Furthermore, the trace over which $\Psi_1$ is evaluated has size bounded by $|\mathcal{T}|$. Since $|\Psi| = |\Psi_1| + 1$, we conclude that the algorithm stores at most $|\Psi| \cdot |\mathcal{T}|$ cuts.

- If $\Psi = \Psi_1 \cup \Psi_2$, then assume that $\Psi$ is evaluated on the run $\sigma$. By induction hypothesis, the number of cuts stored in memory when evaluating $\Psi_1$, resp. $\Psi_2$, on sub-sequences of $\sigma$ is bounded by $|\mathcal{T}| \cdot |\Psi_1|$, resp. $|\mathcal{T}| \cdot |\Psi_2|$. Furthermore, $\Psi_1$ and $\Psi_2$ are evaluated on traces with size bounded by $|\mathcal{T}|$. Since $|\Psi_1| < |\Psi|$ and $|\Psi_2| < |\Psi|$, we conclude that the number of cuts stored in memory by the algorithm when checking $\Psi$ is bounded by $|\Psi| \cdot |\mathcal{T}|$.

- Finally, in the case where the algorithm has to evaluate a formula $\Psi$ on the trace $C_0 \ldots C_k$ that is not of the form $\neg \Psi_1$, $\Psi_1 \lor \Psi_2$, $\bigcirc \Psi_1$ or $\Psi_1 \cup \Psi_2$, then the algorithm evaluates $\Psi$ on $C_0$ as explained above and we directly conclude from the previous cases.

From Propositions 1 and 2, and since $\mathsf{CTL}$ is a subset of $\mathsf{CTL}^*$, we conclude that the following theorem holds.

**Theorem 1** The model checking problem over po-trace is PSPACE-complete for $\mathsf{CTL}^*$ and $\mathsf{CTL}$.

### 5 LTL Model Checking

We now prove that the model checking problem for the linear-time temporal logic LTL is coNP-complete on po-traces. For that purpose, we examine the dual problem of model checking LTL\(^3\) formulae, i.e. formulae of the form $\exists \Phi$ where $\Phi$ is a restricted path formula, as defined in the grammar of LTL. We first show that this problem is NP-easy.

**Proposition 3** The model checking over po-traces is NP-easy for LTL\(^3\)

**Proof.** We exhibit a non-deterministic polynomial time algorithm. The algorithm works as follows: it first guesses a run $\sigma$ of the po-trace $\mathcal{T}$, and then checks that the formula holds on that run. The algorithm starts from $C' = \emptyset$, and for each cut of the run it guesses an event $e$, checks that $e \in \text{enabled}(C')$ and then builds the next cut $C' \cup \{e\}$. The test $e \in \text{enabled}(C')$ can be achieved in polynomial time by enumerating the events of $C'$ to ensure that $e \notin C'$ and then enumerate the elements of $\preceq$ (together with those of $C'$) to ensure that $e' \preceq e$ implies that $e' \in C'$. Finally, note that the size of a run in $\text{runs}(\emptyset)$ has size $|E|$.

Finally, LTL model-checking on a run can solved in polynomial time [7, Proposition 3.3].
Next, we show that the model checking problem is NP-hard for $LTL^3$. For that, we reduce the global predicate detection which is known NP-complete [1]. In our framework, this problem can be stated as follows. Given a po-trace $T$ and a PBF $\phi$ over $P(T)$, the global predicate detection consists in determining if $\exists C \in \text{cuts}(T) : \langle T, C \rangle \models_C \phi$.

**Proposition 4** The model checking problem over po-traces is NP-hard for $LTL^3$.

**Proof.** Given a po-trace $T$, and a PBF $\phi$, it is immediate that $\exists C \in \text{cuts}(T) : \langle T, C \rangle \models_C \phi$ if and only if $T \models \exists (\top U \phi)$. □

We can therefore conclude that the model checking problem is NP-complete for $LTL^3$ and therefore coNP-complete for $Ltl^*$ as stated in the following theorem.

**Theorem 2** The model checking problem over po-traces is coNP-complete for $Ltl^*$.

Hence theorem 1 and 2 show that contrarily to complete systems (Kripke structures) [2], over po-traces, $Ltl^*$ has a lower complexity that $Ctl^*$ and $Ctl$.

**References**


